

Punyashlok Ahilyadevi Holkar Solapur University, Solapur



NAAC Accredited-2022
'B'' Grade (CGPA 2.96)

Name of the Faculty: Science & Technology

New Education Policy 2020

Syllabus: Electronics

Name of the Course: M. Sc. I (Sem.– I & II)

(Syllabus to be implemented from June 2023)

Punyashlok Ahilyadevi Holkar Solapur University, Solapur

M.Sc. Electronics based on NEP-2020

(w.e.f. June 2023-24)

1. Title of the Course: M.Sc.- Electronics

2. Introduction:

Master of Science (M.Sc.) in Electronics is a programme running at Post Graduate Department of Electronics, Shankarrao Mohite Mahavidyalaya, Akulj from June 2006, affiliated to Punyashlok Ahilyadevi Holkar Solapur University, Solapur, and disseminating knowledge of the subject from fundamental concepts to State-of- technologies. With the view to provide exposure to the recent technologies of various sectors of the Electronics and to empower the students to make them competent for industrial needs, R & D sectors and self employment as well the curriculum is framed. Indeed, the curriculum encompasses knowledge of Embedded System and Instrumentation, Communication Electronics and VLSI design and technologies. On collaboration with American companies, the Cypress Semiconductor USA, MicroSemi USA and ARM University London the laboratories for respective specialization are established. Therefore, the student can realize the state-of art of the technological designing and development. The Choice Based Credit System (CBCS) is implemented for this course. In addition to M. Sc.-Electronics, the research programmes M.Phil. as well as Ph.D. are also going on.

3. Objectives of the course:

Following are objectives of the course.

- To provide exposure to the students to the recent technologies.
- To provide the knowledge of design and implementation of instrumentation of significant preciseness.
- To inculcate awareness among the student to perform the projects of industrial standards, which could also, ensures the interdisciplinary approach.
- To empower the students to cater the needs of industrial sectors. It is also attempted to expose the students to the research activities and to inculcate the research awareness.
- To expose the students to the industrial environment a on job training and internship may be provided
- To empower the students to achieve the success in the NET/GATE/SET etc examinations.

4. Advantages of the Course:

Electronics is the subject, which ensures wide application potential in diverse sectors. Along with the basic sciences, it bears the knowledge of technology as well. Therefore, it depicts the tremendous opportunities in the electronic industrial sectors. It ensures well confluence of Science and Technology. Therefore, the course helps to achieve all round development. Moreover, the students can also opt for education field for their career. The students of M. Sc. - Electronics can opt one of the three specializations for part- II.

5. Eligibility of the Course:

- B. Sc. with Electronics subject at Principal/ Interdisciplinary/ Allied/ Applied/ Subsidiary level.
- B. Sc. Physics with Electronics subject at subsidiary Level.
- B.Sc. with Computer Science / B.Sc. Entire Computer Science (BCS).
- Bachelor of Engineering with Electronics / E & TC.

6. Fee Structure: This MSc Electronics course is non-grantable. Therefore, fee structure is as per Rules and Regulations of Punyashlok Ahilyadevi Holkar Solapur University, Solapur.

7. Intake Capacity: 24

8. Duration: 2 Years (4 Semesters)

9. The Choice Based Credit System (CBCS):

A Choice based credit system (CBCS) is implemented for this course. According to this system, choice is given to the students. In fact, the department offers three specializations Embedded System and Instrumentation (ESI), Communication Electronics (CE) and VLSI design (VD). Students can opt any one out of three at Semester-III and IV

10. The Credit and Grading System (CGPA):

Credit is a numerical value that indicates student's work load (lectures, lab work, seminars, tutorial, field work, etc.) to complete a course unit. In most of the universities 15 contact hours constitute one credit. As per the present norms there are 4 contact hours per paper per subject per week, which works out to be 60 contact hours per paper per subject per semester. By converting these contact hours into credit at the rate of 15 contact hours for one credit, there will be 04 credits per paper per subject per semester. There are four papers at PG level. The PG student must complete minimum of 16 credits (maximum 160 credit points) in each semester.

A) Conversion of marks into Grades: A table for the conversion of the marks obtained by a student in each paper (out of 100) to grade and grade points is given below.

Sr. No	Range of Marks	Grade	Grade Point	CGPA
1.	85-100	O	10	9.50-10
2.	75-84	A+	9	8.50-9.49
3.	65-74	A	8	7.50-8.49
4.	55-64	B+	7	6.50-7.49
5.	50-54	B	6	5.50-6.49
6.	40-49	C	5	5.00-5.49
7.	0-39	F (Fail)	Zero	0.0-4.99
8.	Absent	-	Zero	--

Class Chart: The candidate securing minimum of 40% marks in each head of passing shall be declared as successful candidate and the percentage of marks class shall be as follows:

1. 40-49.99% ... Pass Class
2. 50-54.99% ... Second Class
3. 55-59.99% ... B+ Second Class
4. 60-69.99% ... First Class
5. 70% and above ... First Class with Distinction.

1. Grade Point Average at the end of the Semester (SGPA)

$$SGPA = \frac{(G_1 \times C_1) + (G_2 \times C_2) + \dots}{\sum C_i}$$

($\sum C_i$ - The total number of credits offered by the student during a semester)

2. Cumulative Grade Point Average (CGPA)

$$CGPA = \frac{(G_1 \times C_1) + (G_2 \times C_2) + \dots}{\sum C_i}$$

($\sum C_i$ - the total number of credits offered by the student upto and including the semester for which CGPA is calculated.)

3. Final Grade Point Average (FGPA) will be calculated in the similar manner for the total number of credits offered for completion of the said course.

Where: C_i : Credits allocated for the i th course

G_i : Grade point scored in i th paper

- B) Scheme of evaluation:** The candidate has to appear for Internal Evaluation of 20/10 marks and External Evaluation (University Exam) for 80/40 marks for each paper/practical. The nature of internal evaluation will be decided by the Post Graduate Department of Electronics. The internal evaluation comprises unit tests, tutorials, seminars, Group discussion, oral, etc., which ensures a process of continuous assessment.
- C) Nature of Question Papers:** The nature of question paper shall be as per time to time prescribed by the university authorities. The complete question paper has objective type questions, short answer type questions and long answer type questions.
- D) Passing Standard:** The student has to secure a minimum of 4.0 grade points (Grade C) in each paper. A student who secures less than 4.0 grade point (39% or less marks, Grade FC/FR) will be declared fail in that paper (subject) and shall be required to reappear for respective paper. A student who failed in Term End Examination (Theory) & passed in Internal assessment of a paper (subject) shall be given FC Grade. Such student will have to appear for Term End Examination only. A student who fails in Internal assessment and passed in Term End examination (Theory) shall be given FR Grade. Such student will have to appear for Term End examination as well as internal assessment. In case of year down candidates from the mark scheme the candidates shall appear for the same 80 marks paper of the external examination and his performance shall be scaled to 100 marks.
- E) ATKT:** A student who fails in one fourth (25%) or less papers of the total papers offered in the 1st and 2nd semester will be allowed for admission to second year (Sem. III-IV)

11. Structure of the Course:

The Course Structure of M.Sc. Electronics is as depicted in the table. It is integrated course of 2 years i.e. 4 semesters. For, M. Sc. I, each semester bears four compulsory theory papers and Two practical papers. Moreover, for M.Sc.-II two papers are compulsory for each semester and two papers are from specialization out of which one is elective. There are following three specializations and student has to opt one of it.

Specializations:

- a) Embedded System and Instrumentation (ESI)
- b) Communication Electronics (CE)
- c) VLSI Design (VD)

Punyashlok Ahilyadevi Holkar Solapur University, Solapur
Faculty of Science and Technology
Proposed structure for Two Year PG Program (M.Sc.- Electronics) Degree
M.Sc. Electronics (Embedded System and Instrumentation / Communication
Electronics /VLSI Design)

M.Sc. I Electronics

Level/ Difficulty	Sem.	Major		RM	FP/RP/OJT/ Internship/ Apprenticeship	Credits	Cumulative Credits
		Mandatory	Elective				
6.0/400	I	DSC1-1 (4+2) Advanced Microcontrollers	DSE1-1 (4+2) 1. Virtual Instrumentation	Research Methodology (4)	---	22	44 PG Diploma in Discipline
		DSC1-2 (4+2) Industrial Power Electronics	2. Numerical Methods				
	II	DSC1-3(4+2) Modern Control Theory	DSE1-2 (4+2) 1. Signals and Systems	---	OJT/In-house Project/ Internship/ Apprenticeship (4)	22	
		DSC1-4 (4+2) Real Time Operating System	2. Cellular and Mobile communication				
	Total 1 Yrs	24	12	04	04	44	
Exit option: Award of UG degree in Major with 132 Credits OR Continue with Major							

Abbreviations: DSC: Discipline Specific Core, DSE: Discipline Specific Elective, RM: Research Methodology, OJT: On job training internship/Apprenticeship, FP: Field project

M.Sc. II Electronics for ESI (Embedded System and Instrumentation)

Level/ Difficulty	Sem.	Major		RM	FP/RP/OJT/ Internship/ Apprenticeship	Credits	Cumulative Credits
		Mandatory	Elective				
6.5/400	III	DSC1-5 (4+2) Digital Signal Processing	DSE1-3 (4+2) 1. Advanced Digital Design with VHDL 2. Medical Instrumentation	--	RP (4)	22	88 PG Degree in Discipline
		DSC1-6 (4+2) ARM Microcontroller and System Design					
	IV	DSC1-7 (4+2) Networking and Data Communication	DSE1-4 (4+2) 1. Microwave Devices, Antennas and Measurements 2. Device Drivers and Embedded System	--	RP (6)	22	
		DSC1-8 (4) Mechatronics and Industrial Automation					
	Total 2 Yrs	46	24	04	14	88	

M.Sc. II Electronics for CE (Communication Electronics)

Level/ Difficulty	Sem.	Major		RM	FP/RP/OJT/ Internship/ Apprenticeship	Credits	Cumulative Credits
		Mandatory	Elective				
6.5/400	III	DSC1-5 (4+2) Digital Signal Processing	DSE1-3 (4+2) 1. Fundamentals of Optoelectronics 2. Advanced Digital Design with VHDL	--	RP (4)	22	88 PG Degree in Discipline
		DSC1-6 (4+2) Digital Communication					
	IV	DSC1-7(4+2) Networking and Data Communication	DSE1-4 (4+2) 1. Wireless Sensor Network 2. Optical Fiber Communication	--	RP (6)	22	
		DSC1-8 (4) Microwave Devices, Antennas and Measurements					
	Total 2 Yrs	46	24	04	14	88	

Abbreviations: DSC: Discipline Specific Core, DSE: Discipline Specific Elective, RM: Research Methodology, OJT: On job training internship/Apprenticeship, FP: Field project

M.Sc. II Electronics for VD (VLSI Design)

Level/ Difficulty	Sem.	Major		RM	FP/RP/OJT/ Internship/ Apprenticeship	Credits	Cumulative Credits
		Mandatory	Elective				
6.5/400	III	DSC1-5 (4+2) Digital Signal Processing	DSE1-3 (4+2) 1. Nanoelectronics & Nanosystems 2. Advanced Digital Design with VHDL	--	RP (4)	22	88 PG Degree in Discipline
		DSC1-6 (4+2) CMOS Technologies & Analog Circuit Design					
	IV	DSC1-7(4+2) Networking and Data Communication	DSE1-4 (4+2) 1. Smart Fusion Technology Based System Design 2. Microwave Devices, Antennas and Measurements	--	RP (6)	22	
		DSC1-8 (4) Mixed Signal Based SoC Design					
	Total 2 Yrs	46	24	04	14	88	

Abbreviations: DSC: Discipline Specific Core, DSE: Discipline Specific Elective, RM: Research Methodology, OJT: On job training internship/Apprenticeship, FP: Field project

Punyashlok Ahilyadevi Holkar Solapur University, Solapur

Class : M. Sc.-I, Semester : I

Subject : Electronics

Paper Code : DSC1-1: Advanced Microcontrollers

Credit: 4 (Periods: 60)

Unit 1: PIC Microcontrollers

12

Introduction: Advantages of PIC microcontrollers over MCS-51 series. PIC microcontroller features, Architecture of PIC microcontrollers, Pin Description, 16CXX series. Architecture of 16F877. Memory structure, Registers, Register file structure, Register banks, program and data memory, Use of EEPROM, SFRs, W-register, Status register, Option register etc. Interrupts in PIC microcontrollers, IO ports of 16F877. Timers of PIC Microcontrollers, Compare capture mode, PWM mode, I2C bus, On Chip ADC and DAC facility. USART the serial IO, watchdog timer, Power up timer, Sleep mode, Reset, and clock circuits, types of the RESET. Interrupt vector table. Introduction of 18FXX series.

Instruction Set : Instruction set, instruction format, byte oriented instruction, bit oriented instruction, literal instruction, flow control instruction. Addressing modes

Unit 2: Integrated Development Tools for PIC

06

Overview of MPLAB the IDE for Assembly language. Micro C the IDE for embedded C programming. Developing, compiling, and programming the microcontroller, Some programs on IO port, timer and serial IO programming.

Unit 3: AVR Microcontrollers

12

Introduction to AVR: General architecture of AVR microcontroller family. Salient features, AVR Series.

Architecture: Architecture and hardware resources of AVR ATmega 8L, The arithmetic logic unit, program memory & data memory, Downloadable Flash program memory, SRAM data memory, General-purpose register file, SFRs, I/O register, EEPROM data memory, IO port structure, Peripherals, timer and counters, watchdog timer, Serial Peripheral interface, universal asynchronous receiver and transmitter, Analog comparator, reset and interrupt, interrupt vector table, reset sources. On chip ADC and DAC, Reset circuit and clock circuit.

Instruction set: Instruction set, Memory addressing modes, Register direct addressing, I/O direct addressing, SRAM direct addressing, SRAM indirect addressing constant addressing using the LPM instruction, Arithmetic instruction, Logical and bit wise instructions, Jumps and calls, instruction set, reset and interrupt handling, watchdog handling, stack, program constructs, conditional branches, program loops, refreshing port pins and important register, polling inputs.

Unit 4: Integrated Development Tools for AVR

05

Study of development tools of ATMEL AVR microcontrollers, ATMEL AVR Studio, WinAVR and Codevision

Unit 5: Programming and interfacing with AVR & PIC

10

Interfacing with AVR and PIC microcontrollers: Interfacing of IO devices to the ports. Memory interface I/O Interface Interfacing smart LCD, relay, opto-coupler, Interfacing ADC & DAC, firing of thyristor,.

Development of embedded system for: a. Temperature controlling, b. Measurement of pH and c. DC Motor controlling by using PWM techniques.

Reference Books:

1. PIC Microcontrollers and Embedded systems using Assembly and C for PIC18 – M.A. Mazidi, R. D. Mckinlay and D. Causey - Pearson Education, New Delhi- 2009.
2. Embedded design with PIC18F452, John B. Peatman
3. Embedded C programming and the Microchip PIC – Richard Barnett, L.O.Cull and S. Cox Delmer.
4. Microcontrollers Theory and Application – Ajay V. Deshmukh TMH New Delhi
5. Embedded C Programming and the Atmel AVR, R. H. Banett, S. A. Cox, Larry D. O’Cull, Thomson.
6. Programming and customizing The AVR Microcontroller, Dhananjay Gadre, TMH.

Punyashlok Ahilyadevi Holkar Solapur University, Solapur

Class : M. Sc.-I, Semester : I

Subject : Electronics

Paper Code: DSC1-2: Industrial Power Electronics

Credit: 4 (Periods: 60)

Unit 1: Controlled Rectifier

12

- Concept of uncontrolled and controller rectifiers.
- Single phase circuits: Half & Fully controlled bridge rectifier with resistive R & R-L load with and without freewheeling diode, series & dual converter, power factor improvement.
- Three phase circuits: Half controlled rectifier, Half controlled Bridge rectifier, Fully controlled Bridge rectifier with R & R-L load, three phase dual converter.

Unit 2: AC Voltage Controllers

08

- Introduction to AC Voltage controllers AC On / Off control, Effect of duty cycle.
- Concept of Phase control, Single Phase Uni-directional and bidirectional controllers with resistive & inductive loads.
- Three phase half & full wave controllers with resistive & inductive loads.

Unit 3: Inverters

08

- Operating principle. Single phase bridge inverter, steady state analysis. McMurray half and full bridge inverter, McMurray-Bedford half and full bridge inverter
- Three phase inverter, PWM inverters, single phase PWM and Multiphase PWM inverters. Reduction of harmonics.
- Current source inverters single phase current source inverters with R load.

Unit 4: Choppers

07

- Operating principle, control strategies, time ratio control, step –up and step down chopper with R load, Class A, B, C, D, E Choppers
- Multiphase choppers and AC choppers.

Unit 5: Cycloconverter

10

- Introduction to cycloconverter, types of cycloconverter.
- Single Phase Cycloconverter, Mid point cycloconverter, Bridge type cycloconverter, step up cycloconverter.
- Three phase cycloconverters. Three phase to single phase, three phase to three phase. Reduction of output harmonics.
- Microcontroller based firing schemes.

Reference Books:

- Power Electronics – M.H. Rashid, PHI.
- Power Electronics –Singh – Kanchandani- TMH
- Industrial and Power Electronics – Deodatta Shingare Electrotech publication,
- Power Electronics – P. S. Bhimra Khanna publisher, New Delhi.

Punyashlok Ahilyadevi Holkar Solapur University, Solapur

Class : M. Sc.-I, Semester : I

Subject : Electronics

Paper Code : DSE1-1: Virtual Instrumentation

Credit: 4 (Periods: 60)

Unit 1: Fundamentals of Virtual Instrumentation.

10

Historical perspectives, Basic concept of Virtual Instrumentation, Block diagram and architecture of Virtual Instrumentation, data- flow techniques, graphical programming in data flow, Comparison between Virtual instrumentation and Traditional Instrumentation, Advantages of Virtual Instrumentation. Development of VI using GUI.

Unit 2: PC communication Ports

12

Introduction to Centronics parallel ports, Serial COM1/COM2, RS232 standards, Current loop, RS232/RS485, GPIB, Bus Interface: USB, PCI. Networking for office & Industrial applications VISA and IVI .

Unit 3: Add on Peripheral cards

08

Selection & applications , ADC, DAC, DIO, DMM, Waveform Generator.

Unit 4: LABVIEW based Virtual Instrumentation

10

Introduction to LABVIEW the virtual Instrumentation software, Virtual Instrumentation programming techniques, “G” Programming Language, VI and sub-VI loops, charts, arrays, clusters and graphs, case and sequence structures, formula nodes, local and global variables, string and file IO

Unit 5: Case studies

05

Designing of Virtual Instrumentation using LABVIEW for

- a. Data Acquisition Systems for Measurement of physical parameters
- b. Temperature controlling
- c. Biomedical Instrumentation.

Reference Books:

1. LABVIEW Graphical programming Gary Johnson, 2nd Edition, MGH, 1997.
2. LABVIEW for everyone –Lisa K wells and Jeffery Travis PHI 1997.
3. Basic concept of LABVIEW 4-Skoff-PHI 1998.
4. “PC Interfacing for Data Acquisition and process control-S. Gupta & Joseph John A-2nd Edn.1994

Punyashlok Ahilyadevi Holkar Solapur University, Solapur

Class : M. Sc.-I, Semester : I

Subject : Electronics

Paper Code : DSE1-1: Numerical Methods

Credit: 4 (Periods: 60)

Unit 1: System of Linear Algebraic Equations

12

- Formulation of system of linear algebraic equations using matrix and vector notations. Matrix transformations, adjoint and co-factors, Determinant of matrix, Inverse of matrix, Identification of square, Singular, upper-triangular(U), lower triangular(L), tri-diagonal, matrices, Fundamentals of Eigen Value Problem.
- Direct methods:** Forward and Backward Substitution, Gauss Jordan elimination method, Gaussian Elimination method and LU factorization method. Introduction to Iterative method.
- Case Study:** Study of R-2R ladder network using tri-diagonal system.

Unit 2: Laplace Transform

10

- Introduction to Integral transform Laplace transform and its importance to study electrical circuits.
- Laplace transform of standard functions, properties of Laplace transform, Laplace transform of periodic functions,
- Inverse Laplace transform, Partial fraction rule.
- Study of RL, RC, RLC circuits using Laplace transform.

Unit 3: Curve Fitting

10

- Curve fitting:** Introduction to curve fitting. Empirical relation and actual relation.
- Least Squares method of curve fitting :** Straight line fitting, Second order polynomial fitting.
- Interpolation :** Difference between interpolation and extrapolation. Piecewise Linear interpolation, Newton's forward difference formula for interpolation, Newton's backward difference formula for interpolation, Cubic splines approximation. Divided differences for unequal intervals, Lagrangian interpolating polynomials

Unit 4: Numerical Differentiation and Integration

08

- Numerical Differentiation :** Introduction, Forward, central and backward formulae for differentiation,
- Numerical Integration :** Introduction, Newton-Cotes Quadrature formula, Trapezoidal rule, Simpson 1/3 rule and 3/8 rule of numerical integration
- Case Study :** Study of RC differentiator and integrator circuits

Unit 5: Solution of Ordinary Differentiation Equation

05

- Introduction, Initial value problem and boundary value problem.
- Taylor series method, Euler's method , Runge Kutta method.

Reference Books:

- Circuit and Network analysis and synthesis by A. Sudhakar and S. P. Shammohan 2nd Edition, TMH,
- Numerical Method with programming in C 2nd Edition, by T. Veerarajan and T. Ramchandran, TMH, New Delhi.
- Applied Numerical Methods for Engineer, using MATLAB and C, Robert J Schilling and Sandra L Harries, Thompson publishers, 1999.
- Numerical Methods for scientific and Engineering computation by M. K. Jain, S. R. K. Iyengar and R. K. Jain 5th Edn. New Age International, New Delhi.
- A first Course in Numerical Methods by U. M. Ascher and Chen Greif, PHI, New Delhi, 2013.

Punyashlok Ahilyadevi Holkar Solapur University, Solapur

Class : M. Sc.-I, Semester : I

Subject : Electronics

Paper Code : RM : Research Methodology

Credit: 4 (Periods: 60)

Unit 1: Foundation of Research

15

Meaning, Objectives, Motivation, Utility. Types of research: exploratory, descriptive and experimental; Significance and characteristics of research; Criteria of good research, Concept of theory, empiricism, deductive and inductive theory. Characteristics of scientific method- understanding the language of research - Concept, Construct, definition, Variable Research Process.

Unit 2: Problem Identification

15

Definition and formulating the research problem, Necessity of defining the problem, Importance of literature review, need and importance Research Question - Investigation Question - Measurement Issues - Hypothesis - Qualities of a good hypothesis - Null hypothesis & Alternative Hypothesis. Hypothesis Testing - Logic & importance.

Unit 3: Research Design

10

Concept and Importance in Research - Features of a good research design - Exploratory Research Design - Concept, Types and uses, Descriptive Research Design - concept, types and uses. Experimental Design - Concept of Independent & Dependent variables. Qualitative and Quantitative Research: Qualitative - Quantitative Research - Concept of measurement, causality, generalization, replication. Merging the two approaches.

Unit 4: Data collection

10

Data, types of data, methods, sample and population, sampling techniques, characteristics of a good sample; Tools of data collection: observation method, interview, questionnaire, various rating scales, characteristics of good research tools.

Data analysis: Univariate analysis: frequency tables, bar charts, piecharts, percentages; Bivariate analysis: cross tabulations and Chi-square test.

Unit 5: Research writing

10

Report: definition, importance, types; Research paper writing: methods & style; Seminar & conference paper writing; Synopsis writing: methods; Thesis/Project writing: structure & importance; 7 Cs of effective research writing: concreteness, completeness, clarity, conciseness, courtesy, correctness, consideration.

Reference Books:

1. Research Methodology: Methods and Techniques - Kothari, C. R., 2004. New Age International.
2. Research Methodology: An Introduction - Stuart Melville and Wayne, 2014. 2nd edition, Juta Academic.
3. Practical Research Methods - Catherine Dawson, 2002.
4. Research Methodology - Sinha, S. C. and Dhiman, A. K., 2002., Ess Publications.
5. An introduction to Research Methodology - Garg, B. L., Karadia, R., Agarwal, F. and Agarwal, U. K., 2002., RBSA Publishers.
6. Research Methods: the concise knowledge base - Trochim, W. M. K., 2005., Atomic Dog Publishing.

Punyashlok Ahilyadevi Holkar Solapur University, Solapur

Class : M. Sc.-I, Semester : II

Subject : Electronics

Paper Code : DSC1-3: Modern Control Theory

Credit: 4 (Periods: 60)

Unit 1: Fundamentals of Control Systems 8

Introduction The control system , basic definitions, close and open loop system and their comparison, block diagrams, block diagram reduction techniques. Transfer functions and signal flow graphs

Unit 2: Feedback characteristics of control system 10

Feedback and Non feedback system, Reduction of parameter variation using feedback, Control of system dynamics, Control of the effects of disturbance signals using feedback, Regenerative feedback

Unit 3: Time domain analysis and Stability 12

Standard test signals, Time domain performance of control systems, Transient response of the first, the second and the higher order systems, Steady state errors, Effect of adding zero to the system, Design specification of second order system. Concept of poles and zeros. The concept of stability, Necessary conditions for stability Routh stability criterion.

Unit 4: Root locus techniques 06

The Root locus concept, construction of root loci, Root contours, system transportation lag

Unit 5: Frequency domain analysis and stability 10

Correlation between time and frequency response, Polar plots, Bode plots, all pass and minimum phase system, experimental determination of transfer function, log magnitude verses phase plots, Nyquist stability criteria, Assessment of sensitivity analysis in frequency domain.

Unit 6: Control actions and industrial process control 14

Introduction, Process control system, Roll of controllers in process industry, Concept of sequencing and modulating controllers, Control actions, Discontinuous (ON-OFF) and Continuous control modes, Proportional (P), Derivative (D) and Integral (I) controller, Composite (PI, PD, PID) controllers, their performance and characteristics.

Reference Books:

1. Control system Engineering-J.J.Nagrath, M. Gopal, 2nd Edition, Wiley Eastern Ltd.
2. Modern control Engineering-K. Ogata, Prentice Hall of India.
3. Automatic control systems-B.C. Kuo, Prentice Hall of India.
4. Control system –Smarajit Ghosh, Pearson Education (Singapore). Ltd.

Punyashlok Ahilyadevi Holkar Solapur University, Solapur

Class : M. Sc.-I, Semester : II

Subject : Electronics

Paper Code : DSC1-4: Real Time Operating System

Credit: 4 (Periods: 60)

- Unit 1: Overview of Embedded system design with AVR microcontrollers** **15**
- a) **Introduction:** Concept of embedded system, structure of embedded system, characteristics of embedded system, types of embedded system,
 - b) **Microcontroller based embedded system:** Minimum requirement. Microcontroller, Clock circuit, Reset circuit, In system programming (ISP)
 - c) **Embedded system design :** Designing of AVR ATmega8L microcontroller based embedded systems for Measurement of pH, Humidity, wind velocity, temperature etc.
- Unit 2: Fundamentals of Real Time Operating System** **15**
- a) **Introduction:** Concept of Real Time, Real Time operating System, Characteristics of Real-Time operation system, Hard and Soft Real Time Systems.
 - b) **Structure of RTOS:** Structure of RTOS, RTOS Kernel, Kernel Objects, Services of Scheduler.
 - c) **Task :** Task, Task structure, Creation of task, types of task, Task Control block, context, States of task and FSM, idle task, Priority, Static and dynamic priority, Resources, Sharing of resources, ISR, Task Management.
 - d) **Scheduling Algorithm :** Task scheduling Algorithm, preemption, FIFO, Round Robin scheduling, priority based preemptive scheduling. Priority Inversion, Software and hardware time Ticks, context switching.
 - e) Simple programs based on Tiny RTOS kernel.
- Unit3: Task Synchronization and Intertask communication** **15**
- a) **Synchronization of task :** Concept of Sharing of resources, Race condition, Critical condition, deadlocks, spinlocks,
 - b) **Semaphores and mutexes :** Concept of semaphore, Binary semaphore, Counting semaphore, Semaphore management,
 - c) **Mutexes :** Concept of mutex, mutex management.
 - d) **Intertask communication:** Intertask Communication, Messages, Queues, Mailboxes.
- Unit 4: The RTOS Kernel MicroC/OS-II** **05**
- MicroC/OS-II kernel, creation of task, task management, Simple programs on creation of task.
- Unit 5: The RTOS RTLinux** **10**
- RTLinux Kernel, POSIX Pthreads, Processes and Threads, Thread Basics, Process management, semaphores, mutexes. Simple programs on creation of threads.

Reference Books:

1. Embedded C - Michael J Pont
2. Embedded C Programming and the Atmel AVR - R. H. Barnett, S. Cox and L. O'Cull
3. Embedded C Programming and the Microchip PIC - R. H. Barnett, S. Cox and L. O'Cull
4. Operating Systems – A.S. Godbole
5. Real-Time Systems – C.M. Krishna and K.G. Shin
6. Embedded / Real Time Systems – Concepts design – programming- KVVK Prasad.
7. MicroC/OS-II, The Real Time Kernel, - J.J. Labrosse, 2nd Edn. (2006) CMP Books

Punyashlok Ahilyadevi Holkar Solapur University, Solapur

Class : M. Sc.-I, Semester : II

Subject : Electronics

Paper Code : DSE1-2 : Signals And Systems

Credit: 4 (Periods: 60)

Unit 1: Introduction to Signals

18

A Signals, Typical Examples on Signals and systems, classification of signals, continuous-time/discrete-time, deterministic/non-deterministic, periodic, Non-periodic, even-odd, energy-power signals, elementary signals, exponential, sinusoidal, impulse, unit step, ramp, parabolic, Triangular, Rectangular Signals. Basic operations on signals, Time shifting, scaling, Time Reversal, signal addition and signal multiplication.

Unit 2: Introduction to system

18

A System, classification of System, continuous-time and discrete-time system, static and dynamic, linear and non-linear, time-invariant and variant, deterministic and random (stochastic), causal and non-causal, stable and unstable. Linear Time Invariant (LTI) systems, impulse response, convolution integral, convolution sum, condition for BIBO stability for CT and DT signals in terms of impulse response.

Unit 3: Fourier series

12

The Periodic signal, Fourier series Representation of periodic signals, Dirichlet Conditions, Evaluation of Fourier coefficients, symmetry conditions, Half symmetry, amplitude & phase spectrum, Exponential Fourier series, Continuous-time Fourier series (CTFS), properties of CTFS – Parseval's theorem for power signals, power spectral density.

Unit 4: Analysis of Signals and Systems

12

Basic Structure of Matlab, File types, Matlab commands,, tool boxes, Looping and conditioning commands and operators, Matlab command for signals and system problems. Steady state solution of electric circuits with non-sinusoidal periodic inputs using Fourier series – effective values of voltages and currents – power due to nonsinusoidal voltages and currents.

Reference Books:

1. Signals and systems by P. Ramesh Babu, and R Anandanatarajan, SCItch
2. Signal and systems, I J Nagarath , S. N. Shriran and Rakesh Ranjan, TMH 2010
3. Fundamentals of Signals and System, M, J, Robert TMH, 2010
4. Signals and Systems, Richard Buranik

Punyashlok Ahilyadevi Holkar Solapur University, Solapur

Class : M. Sc.-I, Semester : II

Subject : Electronics

Paper Code : DSE1-2 : Cellular and Mobile Communication

Credit: 4 (Periods: 60)

Unit 1: Cellular Radio System Design & Specifications of Analog System

10

A basic cellular system, Performance criteria, Uniqueness of Mobile radio environment, Operation of cellular systems, Definitions of terms and functions of analog system, Specification of Mobile station & Land station, Different specification of the analog cellular system.

Unit 2: Cell Coverage & Antennas

20

Cell coverage- Introduction, Point-to-point model, Foliage loss, Propagation- over flat open area, Near distance, Long distance, Mobile-to-mobile, Cell-site antenna height & signal coverage cells.

Antennas- Cell site antennas, Unique situation of cell-site antennas, Mobile antennas, Design of an Omnidirectional & Directional antenna system

Interference: A) Cochannel interference- Cochannel interference area, Real-time cochannel interference, reduction of cochannel interference B) Nonchannel interference-Adjacent channel interference, Near-end-far-end interference & avoidance of interference, Effect of cell site components

Unit 3: Frequency Management & Channel Assignment

10

Frequency management- Frequency spectrum utilization, Set-up channels, Definition of channel assignment, Fixed channel assignment, Nonfixed channel assignment, Operating with additional spectrum, Traffic and channel assignment.

Handoffs & Dropped calls- Value of implementing handoffs, Initiating handoffs, Delaying a handoffs, Forced handoffs, Queuing of handoffs, Power difference handoffs, Mobile assisted handoffs & soft handoffs, Intersystem handoffs, Introduction to dropped call rate, Formula of dropped call rate.

Unit 4: Operational Techniques & Switching

10

Adjusting the parameters of the system, Hole filler, Leaky feeder, Cell splitting, Microcells. Concept of switching, Analog & Digital switching equipment, Features for handling traffic, MTSO interconnection

Unit 5: Digital Cellular Communication

10

Introduction to digital technology, ARQ techniques, Digital mobile telephony, GSM, Intelligent cell concept, Applications of intelligent micro-cell system

Reference Books:

1. Mobile Cellular Telecommunications Analog Digital System by W.C.Y. Lee, MGH 2nd Ed.
2. Mobile Communication Engineering Theory & Applications by W.C.Y. Lee, MGH 2nd Ed.